



## ***DIGITAL SOFTSTARTER***

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*Modbus Communication Bus*



## **SERIAL COMMUNICATION V5**

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*Communication Manual S/W 2.1 MT0011 Rev. D*

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# *SERIAL COMMUNICATION V5*

# SERIAL COMMUNICATION V5

## CONSIGMENT

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### ❑ RECEPTION

- V5 Series soft-starters are carefully tested and properly packed before leaving the factory.
- In the event of transport damage, please ensure that you notify the transport agency and **POWER ELECTRONICS (+34 96 136 65 57) or your nearest agent**, within 24hrs from receipt of the goods.

### ❑ UNPACKING

Check the V5 Series packing for the following contents:

- V5 Series soft starter. Make sure soft starter model and serial number matches the markings on the box, delivery note and is the correct unit ordered.
- SERIES COMMUNICATION V5 User's Manual.

### ❑ SECURITY

- It is installer's responsibility to ensure the configuration and installation of the V5 Series meets the requirements of any site specific, local and national electrical regulations.
- The V5 Series operates from a HIGH VOLTAGE, HIGH ENERGY ELECTRICAL SUPPLY. Always isolate before servicing.
- Service only by qualified personnel. If you have any service or installation questions please contact Power Electronics Technical Department or your local distributor.
- Always wear safety glasses when operating with the door opened.
- The V5 Series contains static sensitive printed circuit boards. Use static safe procedures when handling these boards.

# *SERIAL COMMUNICATION V5*

## **REVISIONS**

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<b>Date</b>	<b>Revision</b>	<b>Description</b>
January 2002	A	S/W 1.4
January 2003	B	S/W 2.0
March 2004	C	S/W 2.1
December 2017	D	Modbus addresses update G14.1 to 15.8

# SERIAL COMMUNICATION V5

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# SERIAL COMMUNICATION V5

## SERIES COMMUNICATION SPECIFICATIONS.

### HARDWARE: OPTION RS232, PES Part. No. 0401

Physical level RS232	3 cables, optic-isolated communication, full duplex, simple end of RS232
Terminals	28 GND ISO 29 RS232 RX 30 RS232 TX
Output signal level for RS232	' 1' logic < 6.5 respect to 0V ' 0' logic > 6.5 respect to 0V
Input signal level for RS232	' 1' logic < + 0.8V ' 0' logic > + 2.4V ±30 maximum.
Maximum line impedance	2500pF, 3KΩ
Isolation	±100Vcc earth referred.
Maximum equipment number per RS232 net	1
Maximum cable length	15m

### HARDWARE: OPTION RS485, PES Part. No. 0401

Physical level RS485	2 cables, optic-isolated communication, differential-mode, half duplex RS485
Terminals	26 RS485/A 27 RS485/B 28 GND ISO
Input / Output signal level for RS485	' 1' logic = 5 differential ' 0' logic = 5 differential
Isolation	±100Vcc earth referred.
Maximum equipment number per RS485 net	240
Maximum cable length	1000m

## SOFTWARE

Communication Protocol	Standard Modbus Communications
Transmission Mode	RTU (Remote Terminal Unit)
Failures Detection	CRC-16 (Cyclical Redundant Code)
Transmission Speed	Selectable by User between OFF / 1200 / 4800 / 9600
Data length	8 data bits + parity
Parity	Even
Stop Bits	1
Addresses Range	240 unicast addresses (1-240). 15 groupcast addresses (241-255). 1 broadcast address
Response Time	less than 3ms + transmission time
Supported Modbus Functions	3 reading registers 16 writing registers
Supported exception Codes	1. Illegal Function 2. Illegal data Address 3. Illegal data Value 6. Busy, refused message 7. NACK, negative recognition

# SERIAL COMMUNICATION V5

## 1. INTRODUCTION.

The main objective of Series Communication Module of V5 soft-starter is to introduce itself into a compatible net with ModBus communication protocol. This is possible using series communications RS232 or RS485. The series communication module allows V5 soft-starter to be controlled and / or monitoring it like a slave by a ModBus master from a remote location.

The RS485 net allows to connect until 240 equipments to the same net. Nevertheless, RS232 net allows to connect only one unit (slave) to the same net.

The V5 soft-starter functions like a remote slave when is connected to a ModBus system. That means that V5 soft-starter does not start communication task, master will be the who will start such a task.

In practice, all soft-starter running modes, parameters and characteristics are accessible through series communication. For instance, master can give one "Start / Stop order" to soft-starter, or control the soft-starter status, or read the current in motor, ..., at the end, it can access to all soft-starter possibilities.

The series communication module uses RS232 and RS485 standard in the physical level and the industrial ModBus protocol for information exchange.

## 2. INSTALLATION FOR SERIES COMMUNICATION MODULE Ref: E0004 SERIE V5.

1. Switch off the main power supply in order to disconnect the equipment.
2. Insert the PCB to the bottom like figure bellow shows.
3. Switch on the main power supply.

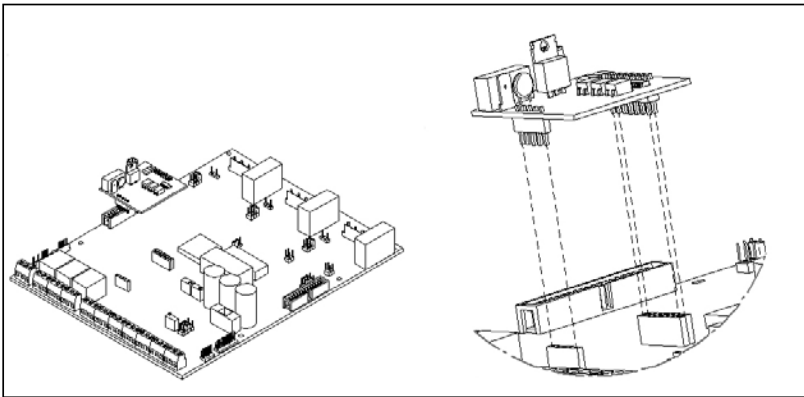


Figure 2.1: Serial Communication Installation.

Series communication module is inserted in the inferior part of control PCB, over 2 female connectors with the followings dimensions 1x5 (lower connector) and 2x7 (upper connector).

**Note:** The series communication module needs separate power supply. This power supply is provided through J1B connector. The power supply voltage must be 9Vef at 50Hz.



# SERIAL COMMUNICATION V5

## RS232 Wiring.

In the following figure an example of a typical wiring for a RS232 connection is shown:

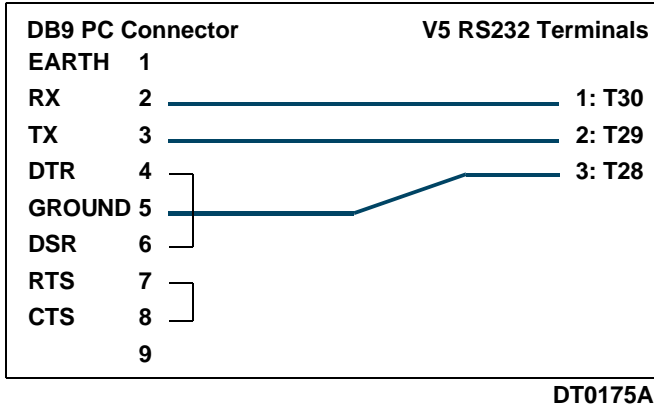


Figure 2.2: RS232 Wiring.

### 3. SUPPORTED MODBUS FUNCTION CODES.

The series communication protocol implemented in the V5 soft-starter adheres itself completely to the standard industrial communication protocol ModBus from Modicon. Of all existing functions in ModBus protocol, the soft-starter uses read-write functions. These functions are the following:

FUNCTION	DESCRIPTION	N° OF REGISTERS
3	READING REGISTERS	10*
16	WRITING REGISTERS	10*

Implementation of this function code in the soft-starter allows reading until 10 registers inside the same Parameter Group in a same frame. In case you need to access to consecutive memory registers which belong to different groups, accesses must be done in so many frames as involved groups.

#### Function Code ModBus n° 3. Registers reading.

This function code allows ModBus controller (master) to read the content of data registers indicated in soft-starter (slave). This function code allows only unicast addressing and it is no possible either broadcast addressing or groupcast addressing

This function code implementation in soft-starter allows to read until 5 soft-starter registers in only one frame.

# SERIAL COMMUNICATION V5

Next it shows an example frame where the master tries to read the content of 3 registers of a soft-starter where the consumed currents per phase are. The information to be attached in question frame is the following:

- Slave data address.
- Function code ModBus (3 reading registers).
- Starting data address.
- N° of registers to be read.
- CRC – 16 code.

Soft-starter (slave) answer should contain the following fields:

- Slave data address.
- Function code ModBus (3 reading registers).
- N° of bytes to be read.
- N° bytes / 2 registers
- CRC-16 code

Each register is composed of 2 bytes (2x8bits=16 bits). This is the standard length for all soft-starter registers.

### Functioning example for function code n°3 (Registers reading).

It can be supposed that we want to read equipment current (data-sheet) through communication system. This data corresponds to parameter G2.1 I EQUIPO. Frame to be transmitted will be:

ModBus Address	Function code ModBus	Starting data address (40022)	Registers number	CRC-16
0AH	03H	00H 15H	00H 01H	94 B5

*Figure 3.2 Example of ModBus frame for function code 3*

It can be supposed that equipment current (data-sheet) is 110A. Slave response will be:

ModBus Address	Function code ModBus	Bytes number	Data (Address 20) (=110)	CRC-16
0AH	03H	02H	6EH	9CH 69H

*Figure 3.3 Example of slave response for a function code 3*

### Function code ModBus n° 16. Registers writing.

This function code allows ModBus controller (master) to write the data registers content indicated by soft-starter (slave), always such register are “Only Read” registers. Please, take into consideration that writing registers by the master does not avoid these registers to be modified (re-write) by the slave later on.

Implementation of this function code in the soft-starter allows to write until 5 soft-starter registers in only one frame.

Continuously, an example frame, where the master tries to write the content of 1 register where the “Acceleration time” is stored, is attached. The information to be attached in question frame is the following:

# SERIAL COMMUNICATION V5

- Slave data address.
- Function code ModBus (16 writing registers).
- Starting data address.
- N° of register to be written.
- N° of bytes to write
- Content of register to write.
- CRC-16 code.

Slave answer contents:

- Slave data address.
- Function code ModBus (16 writing registers).
- Starting data address.
- N° of written registers.
- CRC-16 code.

## 4. V5 SOFT-STARTER REGISTERS

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The following descriptions are of all V5 entries that can be accessed via communications.

### Parameter Group 0: General information screens

Description	L1 Phase Current
V5 parameter	G0.1 L1
Data Address	40185
Data type	r (read)
Units	Amps
Range	0..9999

Description	L2 Phase Current
V5 parameter	G0.1 L2
Data Address	40186
Data type	r (read)
Units	Amps
Range	0..9999

Description	L3 Phase Current
V5 parameter	G0.1 L3
Data Address	40187
Data Type	r (read)
Units	Amps
Range	0..9999

Description	Line Voltage L1-L2
V5 parameter	G0.1 V12
Data Address	40188
Data type	r (read)
Unidades	Volts
Range	0..999

# SERIAL COMMUNICATION V5

<b>Description</b>	<b>Line Voltage L2-L3</b>
V5 parameter	G0.1 V23
Data Address	40189
Data type	r (read)
Units	Volts
Range	0..999

<b>Description</b>	<b>Line Voltage L1-L3</b>
V5 parameter	G0.1 V13
Data Address	40190
Data type	r (read)
Units	Volts
Range	0..999

<b>Description</b>	<b>Supply Frequency</b>
V5 parameter	G0.3
Data Address	40191
Data type	r (read)
Units	Hz
Range	0..99

<b>Description</b>	<b>Power Factor</b>
V5 parameter	G0.3 Cos( $\phi$ )
Data Address	40192
Data type	r (read)
Units	nil
Range	0..100
<b>Note:</b>	<i>Cos(<math>\phi</math>) = Data value of register /100.</i>

<b>Description</b>	<b>Motor Torque</b>
V5 parameter	G0.4
Data Address	40193
Data type	r (read)
Units	%, Motor Torque
Range	0..100

<b>Description</b>	<b>Motor Power</b>
V5 parameter	G0.4
Data Address	40194
Data Type	r (read)
Units	kW
Range	0..999

<b>Description</b>	<b>Relay Status</b>
V5 parameter	G0.5
Data Address	40195
Data type	r (read)
Units	nil
Range	nil
<b>Note:</b>	<i>Activation of relay (X) sets the corresponding bit to 1. Deactivation of relay (0) sets it to 0.</i>
	<b>Byte high:</b> Reserviert <b>Byte low:</b> 7654321
	bit 1 >> Relay 1
	bit 2 >> Relay 2
	bit 3 >> Relay 3

# SERIAL COMMUNICATION V5

<b>Example:</b>	<table border="0"> <tr> <td style="text-align: right;"><b>Value</b></td> <td style="text-align: left;"><b>Status</b></td> </tr> <tr> <td>1 &gt;&gt;</td> <td>X 0 0</td> </tr> <tr> <td>2 &gt;&gt;</td> <td>0 X 0</td> </tr> <tr> <td>4 &gt;&gt;</td> <td>0 0 X</td> </tr> <tr> <td>3 &gt;&gt;</td> <td>X X 0</td> </tr> <tr> <td>7 &gt;&gt;</td> <td>X X X</td> </tr> </table>	<b>Value</b>	<b>Status</b>	1 >>	X 0 0	2 >>	0 X 0	4 >>	0 0 X	3 >>	X X 0	7 >>	X X X
<b>Value</b>	<b>Status</b>												
1 >>	X 0 0												
2 >>	0 X 0												
4 >>	0 0 X												
3 >>	X X 0												
7 >>	X X X												

<p><b>Description</b>  V5 parameter  Data Address  Data type  Units  Range  <b>Note :</b></p>	<p><b>Digital Inputs+PTC motor</b>  G0.6  40196  r (read)  nil  nil</p> <p><i>The activation of a digital Input (X) sets the corresponding bit to 1.  Likewise an input deactivation (0) sets the bit to 0.</i></p>
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<p><b>Byte high:</b> Reserviert  bit 1 &gt;&gt; Digital Input 1  bit 2 &gt;&gt; Digital Input 2  bit 3 &gt;&gt; Digital Input 3  bit 4 &gt;&gt; Digital Input 4  bit 5 &gt;&gt; Digital Input 5  bit 6 &gt;&gt; PTC Motor</p>	<p><b>Byte low:</b> 87654321</p>
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<b>Example:</b>	<table border="0"> <tr> <td style="text-align: right;"><b>Value</b></td> <td style="text-align: left;"><b>Status</b></td> </tr> <tr> <td>32 &gt;&gt;</td> <td>0 0 0 0 0 F</td> </tr> <tr> <td>33 &gt;&gt;</td> <td>X 0 0 0 0 F</td> </tr> <tr> <td>34 &gt;&gt;</td> <td>0 X 0 0 0 F</td> </tr> <tr> <td>36 &gt;&gt;</td> <td>0 0 X 0 0 F</td> </tr> <tr> <td>40 &gt;&gt;</td> <td>0 0 0 X 0 F</td> </tr> <tr> <td>48 &gt;&gt;</td> <td>0 0 0 0 X F</td> </tr> </table>	<b>Value</b>	<b>Status</b>	32 >>	0 0 0 0 0 F	33 >>	X 0 0 0 0 F	34 >>	0 X 0 0 0 F	36 >>	0 0 X 0 0 F	40 >>	0 0 0 X 0 F	48 >>	0 0 0 0 X F
<b>Value</b>	<b>Status</b>														
32 >>	0 0 0 0 0 F														
33 >>	X 0 0 0 0 F														
34 >>	0 X 0 0 0 F														
36 >>	0 0 X 0 0 F														
40 >>	0 0 0 X 0 F														
48 >>	0 0 0 0 X F														

<p><b>Description</b>  V5 parameter  Data Address  Data type  Units  Range</p>	<p><b>Overload Status</b>  G0.7  40197  r (read)  %  0..100%, where 100% overload will cause an Overload fault status on the soft-starter.</p>
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<p><b>Description</b>  V5 parameter  Data Address  Data type  Units  Range  <b>Note :</b></p>	<p><b>Start (Host) Command</b>  40198  r/w (read/write)  nil  0..1</p> <p><i>If G6.1 control mode =3 serial comms has been enabled, writing a 1 to this register starts the soft starter.</i></p>
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<p><b>Description</b>  V5 parameter  Data Address  Data type  Units  Range  <b>Note:</b></p>	<p><b>Stop (Host) Command</b>  40199  r/w (read/write)  nil  0..1</p> <p><i>If G6.1 Control model=3 Serial comms has been enabled, writing 1 to this register sends a STOP command to the soft-starter.</i></p>
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# SERIAL COMMUNICATION V5

<b>Description</b>	<b>Reset (Host) Command</b>
V5 parameter	
Data Address	40200
Data type	r/w (read/write)
Units	nil
Range	0..1
<b>Note:</b>	<i>If G6.1 Control model=3 Serial comms has been enabled, writing 1 to this register sends a RESET command to the soft-starter.</i>

<b>Description</b>	<b>V5 Status</b>
V5 parameter	
Data Address	40201
Data type	r (read)
Units	nil
Range	nil
<b>Note:</b>	<i>Digital inputs on (X) causes 1 in the determined bit</i>
	<b>Byte high:</b> Reserved <b>Byte Low:</b> 87654321
	bit 1 >> V5 Stopped
	bit 2 >> V5 Accelerating
	bit 3 >> V5 Running
	bit 4 >> V5 Decelerating

<b>Description</b>	<b>Fault status</b>
V5 parameter	G10.1
Data Address	40202
Data type	r (read)
Units	nil
Range	0..27
<b>Note:</b>	<i>Also this values are displayed In 7 segment PBUS display.</i>

FAULT	DISPLAY TEST	DESCRIPTION
F0	NO FAULT	No fault.
F1	PHA MISING	Phase input missing.
F2	WRONG PH/SQ	Wrong input phase sequence.
F3	ASYM CURR	Unbalanced current consumption.
F4	OVER LOAD	Excessive current consumption.
F5	UNDER LOAD	Under load motor.
F6	PEAK CURR	The current has been higher than 6 times the nominal.
F7	STARTER OT	Excessive temperature in the radiator (>85°C).
F8	MOTOR PTC	Shoot by the PTC of the motor.
F9	SHEAR PIN	The motor current has reached the Shearpin protection.
F10	OVER VOLT	Too high input voltage.
F11	UNDER VOLT	Too low input voltage for too much time.
F12	EXCESIV STR	Excessive number of starts.
F13	MEMORY FLT	Fault in data memory.
F14	SCR1 FAULT	Thyristor fault in phase L1, disconnected motor in L1.
F15	SCR2 FAULT	Thyristor fault in phase L2, disconnected motor in L2.
F16	SCR3 FAULT	Thyristor fault in phase L3, disconnected motor in L3.
F17	SCR_S FLT	Thyristor fault, disconnected motor.
F18	EXCES T LS	Too much time at slow speed mode.
F19	LS DISABLE	It's not possible to work at Slow Speed mode.
F20	COMS T/OUT	Too much time without Serial Communications.
F21	EXTRN TRIP	An external fault has occurred through a digital input.
F22	CUR FLT	Large current imbalance occurs due to a sudden voltage

## SERIAL COMMUNICATION V5

		drop in any of the V5 input phases.
<b>F23</b>	CUR FLT2	Large current imbalance occurs due to a sudden voltage rise in any of the V5 input phases
<b>F24</b>	HIGH PRESSURE	Overpressure, the V5 is running and the pressure switch opens for longer then the time entered in screen G16.4.
<b>F25</b>	LOW PRESSURE	The V5 is running and the pressure switch opens for longer than the time entered in screen G16.5.
<b>F26</b>	FLOW SWITCH	No water in the pump, then the flow switch is ignored for the time set in screen G16.7 on receipt on a valid start signal.
<b>F27</b>	DEEP WELL PROBE	The tank or pump has not water.

### **Description** **V5 Status Mode**

V5 parameter  
 Data Address 40203  
 Data type r (read)  
 Units nil  
 Range nil

### **Description** **Motor Current**

V5 parameter  
 Data Address 40204  
 Data type r (read)  
 Units % of nominal current of the starter (G.2.1).  
 Range 0..500%

### **Description** **Motor Power**

V5 parameter  
 Data Address 40205  
 Data type r (read)  
 Units % of nominal power of the starter (G.2.4).  
 Range 0.??%

### **Description** **Motor Voltage**

V5 parameter  
 Data Address 40206  
 Data type r (read)  
 Units % of nominal voltage of the starter (G.2.3).  
 Range 0.??%

### **Description** **Analogue input 1**

V5 parameter  
 Data Address 40207  
 Data type r (read)  
 Units %  
 Range 0..100%

### **Description** **Analogue input 2**

V5 parameter  
 Data Address 40208  
 Data type r (read)  
 Units %  
 Range 0..100%

# SERIAL COMMUNICATION V5

Description	Total Current
V5 parameter	
Data Address	40209
Data type	r (read)
Units	A
Range	0..9999

Description	Total Power
V5 parameter	
Data Address	40210
Data type	r (read)
Units	V
Range	0..999

## Parameters Group 1: Menu options

Description	Commissioning
V5 parameter	G1.6
Data Address	40019
Data type	r/w (read/write)
Units	nil
Range	0..1
	0=YES
	1=NO

**Note:** *The rest of screens from this group can only be modify from local display for security reasons.*

## Parameters Group 2: Nameplate

Description	V5 (nameplate) current
V5 parameter	G2.1
Data Address	40022
Data type	r/w (read/write)
Units	Amps
Range	0..1600

Description	Motor (nameplate) Current
V5 parameter	G2.2
Data Address	40023
Data type	r/w (read/write)
Units	Amps
Range	0..1600

Description	Motor(nameplate) Voltage
V5 parameter	G2.3
Data Address	40024
Data type	r/w (read/write)
Units	Volts
Range	0..4
	1 = 220V / 240V
	2 = 380V / 440V
	3 = 460V / 525V
	4 = 660V /690V



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<b>Description</b>	<b>Motor(nameplate) Power</b>
V5 parameter	G2.4
Data Address	40025
Data type	r/w (read/write)
Units	kW
Range	4..999

<b>Description</b>	<b>Motor(nameplate) Phi Cosine</b>
V5 parameter	G2.5
Data Address	40026
Data type	r/w (read/write)
Units	nil
Range	40..99%
<b>Reading example:</b>	Comms value 30 =30%

<b>Description</b>	<b>Mains (nameplate) Frequency</b>
V5 parameter	G2.6
Data Address	40027
Data type	r/w (read/write)
Units	nil
Range	0= 50Hz 1=50/60Hz

### Parameters Group 3: Protections

<b>Description</b>	<b>Phase Sequence</b>
V5 parameter	G3.1
Data Address	40029
Data type	r/w (read/write), stop to set
Units	nil
Range	0=No phase Sequence 1= L1 L2 L3 Sequence 2= Inverse Sequence

<b>Description</b>	<b>Overload Current</b>
V5 parameter	G3.2
Data Address	40030
Data type	r/w (read/write)
Units	Amps
Range	0.6 to 1.5 x I equip
Scale	200= I equip (intensidad nominal del equipo)
<b>Reading example:</b>	Comms value 300 and current 30A (300 x 30 ) / 200 = 45A

<b>Description</b>	<b>Overload Curve</b>
V5 parameter	G3.3
Data Address	40031
Data type	r/w (read/write)
Units	nil
Range	0..10

# SERIAL COMMUNICATION V5

**Description**

V5 parameter  
Data Address  
Data type  
Units  
Range

**Overload Factor**

G3.4  
40032  
r/w (read/write)  
% Overload Curve (G3.3)  
100..500

**Description**

V5 parameter  
Data Address  
Data type  
Units  
Range

**PTC motor**

G3.5  
40033  
r/w (read/write), stop to set  
nil  
0= NO  
1= YES

**Description**

V5 parameter  
Data Address  
Data type  
Units  
Range  
Scale

**Underload Current**

G3.6  
40034  
r/w (read/write)  
Amps  
0 to 0.9 x I equip.  
200= I equip  
*Reading example:* Comms value 180 , current 30A  
 $(180 \times 30) / 200 = 27A$

**Description**

V5 parameter  
Data Address  
Data type  
Units  
Range

**Underload Delay**

G3.7  
40035  
r/w (read/write)  
seconds  
0..99, 100=OFF (verify off)

**Description**

V5 parameter  
Data Address  
Data type  
Units  
Range  
Scale

**Shearpin Current**

G3.8  
40036  
r/w (read/write)  
Amps  
0.6 to 1.2 x I equip.  
200= I equip  
*Reading example:* Comms value 240, current 30A  
 $(240 \times 30) / 200 = 36A$

**Description**

V5 parameter  
Data Address  
Data type  
Units  
Range

**Asymmetrical Current Protection**

G3.9  
40037  
r/w (read/write)  
nil  
0..1  
0 = No  
1 = Yes

# SERIAL COMMUNICATION V5

## Description

V5 parameter  
Data Address  
Data type  
Units  
Range

## Low Voltage

G3.10  
40038  
r/w (read/write)  
Volts

It depends of the motor voltage:

V motor	Range	Scale
220V / 240V	162V – 208V	x 0.5775
380V / 440V	280V - 360V	x 1.0
460V / 525V	350V – 450V	x 1.25
660V / 690V	508V – 653V	x 1.815

## Description

V5 parameter  
Data Address  
Data type  
Units  
Range

## Low Voltage time

G3.11  
40039  
r/w (read/write)  
seconds  
0..10, 11=OFF (verify off)

## Description

V5 parameter  
Data Address  
Data type  
Units  
Range

## Overvoltage

G3.12  
40040  
r/w (read/write)  
Volts  
It depends of the motor voltage:

V motor	Range	Scale
220V / 240V	254V – 266V	x 0.5775
380V / 440V	440V - 460V	x 1.0
460V / 525V	550V – 575V	x 1.25
660V / 690V	798V – 835V	x 1.815

## Description

V5 parameter  
Data Address  
Data type  
Units  
Range

## Overvoltage Timeout

G3.13  
40041  
r/w (read/write)  
seconds  
0..10, 11=OFF (verify off)

## Description

V5 parameter  
Data Address  
Data type  
Units  
Range

## Starts Limit

G3.14  
40042  
r/w (read/write)  
nil  
0..10

## Description

V5 parameter  
Data Address  
Data type  
Units  
Range

## Start Interval

G3.15  
Q40043  
r/w (read/write)  
minutes  
0..60, 61=OFF (verify off)

# SERIAL COMMUNICATION V5

## Parameters Group 4: Acceleration

<b>Description</b>	<b>Start Delay</b>
V5 parameter	G4.1
Data Address	40045
Data type	r/w (read/write)
Units	seg
Range	0..600

<b>Description</b>	<b>Pulse Torque</b>
V5 parameter	G4.2
Data Address	40046
Data type	r/w (read/write)
Units	nil
Range	50..100

<b>Description</b>	<b>Pulse Torque Time</b>
V5 parameter	G4.3
Data Address	40047
Data type	r/w (read/write)
Units	milliseconds
Range	0..9, OFF

<b>Description</b>	<b>Initial Torque</b>
V5 parameter	G4.4
Data Address	40048
Data type	r/w (read/write)
Units	nil
Range	30..99

<b>Description</b>	<b>Initial Torque Time</b>
V5 parameter	G4.5
Data Address	40049
Data type	r/w (read/write)
Units	seconds
Range	0..10

<b>Description</b>	<b>Acceleration Time</b>
V5 parameter	G4.6
Data Address	40050
Data type	r/w (read/write)
Units	seconds
Range	1..180

<b>Description</b>	<b>Current Limit</b>
V5 parameter	G4.7
Data Address	40051
Data type	r/w (read/write)
Units	Amps
Range	1.5..5 x I equip.

# SERIAL COMMUNICATION V5

## Parameters Group 5: Deceleration

<b>Description</b>	<b>Freewheel Stop</b>
V5 parameter	G5.1
Data Address	40053
Data type	r/w (read/write)
Units	no
Range	0..1 0 = No 1 = Yes

<b>Description</b>	<b>Deceleration Time</b>
V5 parameter	G5.2
Data Address	40054
Data type	r/w (read/write)
Units	seconds
Range	0..180

<b>Description</b>	<b>Deceleration Algorithm</b>
V5 parameter	G5.3
Data Address	40055
Data type	r/w (read/write)
Units	no
Range	0..1 0= NORMAL 1=HAMMER ALGORITHM

<b>Description</b>	<b>Hammer Factor</b>
V5 parameter	G5.4
Data Address	40056
Data type	r/w (read/write)
Units	%
Range	1..99

<b>Description</b>	<b>Hammer Torque</b>
V5 parameter	G5.5
Data Address	40057
Data type	r/w (read/write)
Units	%
Range	1..79

## Parameters Group 6: Inputs

<b>Description</b>	<b>Control Mode</b>
V5 parameter	G6.1
Data Address	40059
Data type	r/w (read/write), stop to set
Units	nil
Range	0..5

# SERIAL COMMUNICATION V5

Nr.	MODE	DESCRIPTION	DISPLAY
0	Disable	No control source enabled. There is no way to Start/Stop-Reset the V5.	
1	Local	Start/Stop-Reset enabled by keypad.	L
2	Remote	Start/Stop-Reset enabled by digital inputs.	R
3	Serial Comms	Start/Stop-Reset enabled by serial comms.	C
4	Local Jog V/S	Jog Slow Speed controlled by keypad.	G
5	Pump ctrl-1	Pump control 1 enable.	P

### Description

V5 parameter  
Data Address  
Data type  
Units  
Range

### Local Reset

G6.2  
40060  
r/w (read/write), stop to set  
nil  
0..1  
0 = No  
1 = Yes

### Description

V5 parameter  
Data Address  
Data type  
Units  
Range

### Digital Input 1, 2, 3, 4, 5

G6.3, 4, 5, 6, 7  
40061, 40062, 40063, 40064, 40065  
r/w (read/write), stop to set  
nil  
0..14 (11..14 if G6.1=Pumo ctrl-1, see next page)

Nr.	MODE	STATUS	FUNCTION
0	Not active	NA	Input has no effect.
1	Start	NO	Commands start.
2	Stop	NC	Commands stop.
3	Stop-Reset	NC	Commands stop; Reset on opening edge.
4	Start-Stop	NO	Commands start when closed; Stop when open.
5	Reset	NC	Reset on opening edge.
6	Slow Speed +	NA	Slow Speed +.
7	Slow Speed -	NA	Slow Speed -.
8	DC Brake	NA	Active DC Brake.
9	Dual setting	NA	Active Dual setting.
10	External trip	NC	Error occurs once this contact is opened.

### Description

V5 parameter  
Data Address  
Data type  
Units  
Range

### Analog Input 1 FORMAT

G6.8  
40066  
r/w (read/write)  
nil  
0..2  
0 = 0-20mA;  
1 = 4-20mA;  
2 = 0-10V

## **SERIAL COMMUNICATION V5**

### **Description Digital Input 1, 2, 3, 4, 5**

V5 parameter G6.3, 4, 5, 6, 7

<b>Nr</b>	<b>MODE</b>	<b>STATUS</b>	<b>FUNCTION</b>
11	High pressure	NA	Error for high pressure.
12	Low pressure	NA	Error for low pressure.
13	Flow detec.	NA	Stops for low Flow.
14	Profund. pozo	NA	Stops for low water level.

# SERIAL COMMUNICATION V5

<b>Description</b>	<b>Analog Input 1 Range</b>
V5 parameter	G6.9
Data Address	40067
Data type	r/w (read/write)
Units	nil
Range	0..999

<b>Description</b>	<b>Analog Input 1 Units</b>
V5 parameter	G6.10
Data Address	40068
Data type	r/w (read/write)
Units	nil
Range	0..3
	0 = Bar
	1 = ° C
	2 = Mtr
	3 = OFF

<b>Description</b>	<b>Analog Input 2 Format</b>
V5 parameter	G6.11
Data Address	40069
Data type	r/w (read/write)
Units	nil
Range	0..2
	0 = 0-20mA;
	1 = 4-20mA;
	2 = 0-10V

<b>Description</b>	<b>Analog Input 2 Range</b>
V5 parameter	G6.12
Data Address	40070
Data type	r/w (read/write)
Units	nil
Range	0..999

<b>Description</b>	<b>Analog Input 2 Units</b>
V5 parameter	G6.13
Data Address	40069
Data type	r/w (read/write)
Units	nil
Range	0..3
	0 = Bar;
	1 = ° C;
	2 = m
	3 = OFF

## Parameters Group 7: Outputs

<b>Description</b>	<b>Output Relays 1, 2, 3</b>
V5 parameter	G7.1, 2, 3
Data Address	40073, 40074, 40075
Data type	r/w (read/write), set to stop
Units	nil
Range	1..21



## SERIAL COMMUNICATION V5

RELAY TABLE SELECTION		
MODE	FUNCTION	DESCRIPTION
0	Not active	Relay is disable, not used.
1	Active	Relay is enabled.
2	Warning overload	The motor current exceeds the value adjusted in parameter G3.2 (OVERLOAD CURRENT).
3	Warning under load	The motor current is below the value adjusted in parameter G3.6 (UNDERLOAD CURRENT).
4	Warning over voltage	The mains voltage is equal or higher than G3.12 (OVERVOLTAGE).
5	Warning low voltage	The mains voltage is less or equal than G3.10 (UNDERVOLTAGE).
6	Comparator 1	Relay enables when the value of the parameter set in screen G9.1 is above screen G9.2 value after time set in screen G9.4. Relay disables when the value of the parameter set in screen G9.1 is below screen G9.3 value after time set in screen G9.5.
7	Comparator 2	Relay enables when the value of the parameter set in screen G9.6 is above screen G9.7 value after time set in screen G9.9. Relay disables when the value of the parameter set in screen G9.6 is below screen G9.8 value after time set in screen G9.10.
8	Comparator 3	Relay enables when the value of the parameter set in screen G9.11 is above screen G9.12 value after time set in screen G9.14. Relay disables when the value of the parameter set in screen G9.11 is below screen G9.13 value after time set in screen G9.15.
9	General Fault	Relay will be active a fault occurs.
10	No fault	Will be active if no faults are present (failsafe).
11	Thyristor fault	One or more thyristors are fault.
12	Autoreset Fault	Relay enables when screen G15.2 Attemp numbr setting is passed over.
13	Ready	The soft starter is ready to run the motor.
14	Run	ON at the beginning of the ramp up / OFF at the end of the ramp down.
15	Bypass/React	ON at the end of the ramp up / OFF at the beginning of the ramp down.
16	Delay	ON at the end of the ramp up / OFF at the end of the ramp down.
17	High pressure	The V5 is running and the pressure switch opens for longer than the time entered in screen G16.4
18	Low pressure	The V5 is running and the pressure switch opens for longer than the time entered in screen G16.5.
19	No flow	The flow switch is ignored for the time set in screen G16.6 on receipt of a valid start signal. After this time the V5 will trip if no flow is indicated for longer than the time set in screen G16.7.
20	Low water	The well probe controller (or other level controller) detects a lack of water.
21	Pump fault	A fault from F24 to F27 and F5 has occurred. Pump related faults.

# SERIAL COMMUNICATION V5

**Description**

V5 parameter  
Data Address  
Data type  
Units  
Range

**Analog Output Source Selection**

G7.4  
40076  
r/w (read/write), stop to set  
nil  
0..7

Nr.	DESCRIPTION
0	UNUSED
1	MOTOR CURRENT
2	MOTOR POWER
3	MOTOR TORQUE
4	COSINUS PHI
5	INPUT VOLTAGE
6	ANALOG I 1 ECHO
7	ANALOG I 2 ECHO

**Description**

V5 parameter  
Data Address  
Data type  
Units  
Range

**Analog Output Format**

G7.5  
40077  
r/w (read/write)  
nil  
0..1  
0 = 0 - 20mA  
1 = 4 - 20mA

**Description**

V5 parameter  
Data Address  
Data type  
Units  
Range

**Analogue Output Low Setpoint**

G7.6  
40078  
r/w (read/write)  
% of base selected (G7.5)  
0..500

**Description**

V5 parameter  
Data Address  
Data type  
Units  
Range

**Analogue Output High Setpoint**

G7.7  
40079  
r/w (read/write)  
% of base selected (G7.5)  
0..500

**Parameters Group 8: Dual setting**

**Description**

V5 parameter  
Data Address  
Data type  
Units  
Range

**Dual setting**

G8.1  
40081  
r/w (read/write) stop to set  
no  
0 = NO  
1 = YES

# SERIAL COMMUNICATION V5

**Description**

V5 parameter  
Data Address  
Data type  
Units  
Range

**Torque pulse 2**

G8.2  
40082  
r/w (read/write) stop to set  
no  
50..100

**Descripción**

V5 parameter  
Data Address  
Data type  
Units  
Range  
Scale

**Pulse torque time 2**

G8.3  
40083  
r/w (read/write)  
seconds  
0..9, 0 = OFF  
/10  
Comms value 8 = 0.8 sec

**Reading example:**

**Description**

V5 parameter  
Data Address  
Data type  
Units  
Range

**Initial torque 2**

G8.4  
40084  
r/w (read/write)  
%  
30..99

**Description**

V5 parameter  
Data Address  
Data type  
Units  
Range

**Initial torque time 2**

G8.5  
40085  
r/w (read/write)  
seconds  
0..10

**Description**

V5 parameter  
Data Address  
Data type  
Units  
Range

**Acceleration time 2**

G8.6  
40086  
r/w (read/write)  
segundos  
1..180

**Description**

V5 parameter  
Data Address  
Data type  
Units  
Range  
Scale

**Current limit 2**

G8.7  
40087  
r/w (read/write)  
Amps  
1,5 a 5 x I equip  
200= I equipo (intensidad nominal del equipo)  
Comms value 735 , current 30A  
(735 x 30 ) / 200 = **110.25A**

**Reading example:**

**Description**

V5 parameter  
Data Address  
Data type  
Units  
Range

**Freewheel stop 2**

G8.8  
40088  
r/w (read/write)  
no  
0 = NO  
1 = YES

# SERIAL COMMUNICATION V5

## **Description**

V5 parameter  
Data Address  
Data type  
Units  
Range

## **Deceleration time 2**

G8.9  
40089  
r/w (read/write)  
seconds  
1..180

## **Description**

V5 parameter  
Data Address  
Data type  
Units  
Range

## **Motor deceleration algorithm 2**

G8.10  
40090  
r/w (read/write)  
no  
1 = NORMAL  
2 = HAMMER PREVENT

## **Description**

V5 parameter  
Data Address  
Data type  
Units  
Range

## **Hammer factor 2**

G8.11  
40091  
r/w (read/write)  
%  
1..99

## **Description**

V5 parameter  
Data Address  
Data type  
Units  
Range

## **Minimum torque 2**

G8.12  
40092  
r/w (read/write)  
%  
1..99

## **Description**

V5 parameter  
Data Address  
Data type  
Units  
Range

## **Phase sequence 2**

G8.13  
40093  
r/w (read/write), stop to set  
no  
1 = NO SEQ PROTEC  
2 = L1 L2 L3 SEQ  
3 = INVERSED SEQ.

## **Description**

V5 parameter  
Data Address  
Data type  
Units  
Range  
Scale

## **Overload motor current 2**

G8.14  
40094  
r/w (read/write)  
Amps  
0.6 x I equip to 1.5 x I equip  
200= V5 Current  
Comms value 300, current 30A  
(300 x 30 ) / 200 = 45A

## **Reading example:**

## **Description**

V5 parameter  
Data Address  
Data type  
Units  
Range

## **Overload curve 2**

G8.15  
40095  
r/w (read/write)  
no  
1..10

# SERIAL COMMUNICATION V5

**Description**

V5 parameter  
Data Address  
Data type  
Units  
Range

**Starting overload factor 2**

G8.16  
40096  
r/w (read/write)  
% overload curve (G3.3)  
100..500

**Description**

V5 parameter  
Data Address  
Data type  
Units  
Range

**Motor PTC 2**

G8.17  
40097  
r/w (read/write), stop to set  
no  
0= NO  
1= YES

**Description**

V5 parameter  
Data Address  
Data type  
Units  
Range  
Scale

**Underload current 2**

G8.18  
40098  
r/w (read/write)  
Amps  
0 a 0.9 x I equip  
200= V5 current  
Comms value 180, current 30A

**Reading example:**

**Description**

V5 parameter  
Data Address  
Data type  
Units  
Range

**Underload delay 2**

G8.19  
40099  
r/w (read/write)  
seconds  
0..99, 100=OFF

**Description**

V5 parameter  
Data Address  
Data type  
Units  
Range  
Scale

**Shearpin current 2**

G8.20  
40100  
r/w (read/write)  
Amps  
0.6 x I equip. to 1.2 x I equip.  
200= V5 current  
Comms value, current 30A  
(240 x 30) / 200 = 36A

**Reading example:**

**Description**

V5 parameter  
Data Address  
Data type  
Units  
Range

**Asymmetrical current 2**

G8.21  
40101  
r/w (read/write)  
no  
0..1  
0 = NO  
1 = YES

## SERIAL COMMUNICATION V5

### Description

V5 parameter  
Data Address  
Data type  
Units  
Range

### Motor Current 2

G8.22  
40102  
r/w (read/write)  
Amps  
1 to 1600

### Description

V5 parameter  
Data Address  
Data type  
Units  
Range

### Motor Voltage 2

G8.23  
40103  
r/w (read/write)  
Volts  
1 = 220V / 240V  
2 = 380V / 440V  
3 = 460V / 525V  
4 = 660V / 690V

### Description

V5 parameter  
Data Address  
Data type  
Units  
Range

### Motor Power 2

G8.24  
40104  
r/w (read/write)  
kW  
4..999  
Comms value 41 = 4.1kW

### Write example:

### Description

V5 parameter  
Data Address  
Data type  
Units  
Range

### Motor Cos Phi 2

G8.25  
40105  
r/w (read/write)  
no  
40..99  
Comms value 30 = 30%

### Write example:

### Description

V5 parameter  
Data Address  
Data type  
Units  
Range

### Supply frequency 2

G8.26  
40106  
r/w (read/write)  
no  
0= 50Hz  
1=50/60Hz

## Parameters Group 9: Comparators

### Description

V5 parameter  
Data Address  
Data type  
Units  
Range

### Comparator Source Selection

G9.1  
40108  
r/w (read/write)  
nil  
0..8

# SERIAL COMMUNICATION V5

Nr.	SOURCE
0	UNUSED
1	MOTOR CURRENT
2	MOTOR POWER
3	MOTOR TORQUE
4	COSINUS PHI
5	INPUT VOLTAGE
6	ANALOG INPUT 1
7	ANALOG INPUT 2
8	O/LOAD STATUS

**Description**

V5 parameter  
Data Address  
Data type  
Units  
Range

**Comparator ON Setpoint**

G9.2  
40109  
r/w (read/ write)  
% of function selected (G9.2)  
0..500

**Description**

V5 parameter  
Data Address  
Data type  
Units  
Range

**Comparator OFF Setpoint**

G9.3  
40110  
r/w (read/write)  
% of function selected (G9.2)  
0..500

**Description**

V5 parameter  
Data Address  
Data type  
Units  
Range

**Comparator ON Delay**

G9.4  
40111  
r/w (read/write)  
seconds  
0..99

**Description**

V5 parameter  
Data Address  
Data type  
Units  
Range

**Comparator OFF Delay**

G9.5  
40112  
r/w (read/write)  
seconds  
0..99

**Description**

V5 parameter  
Data Address  
Data type  
Units  
Range

**Comparator 2 Source Selection**

G9.6  
40113  
r/w (read/write)  
nil  
0..8 (See table G9.1)

**Description**

V5 parameter  
Data Address  
Data type  
Units  
Range

**Comparator 2 ON Setpoint**

G9.7  
40114  
r/w (read/ write)  
% of function selected  
0..500

## SERIAL COMMUNICATION V5

<b>Description</b>	<b>Comparator 2 OFF Setpoint</b>
V5 parameter	G9.8
Data Address	40115
Data type	r/w (read/write)
Units	% of function selected
Range	0..500

<b>Description</b>	<b>Comparator 2 ON Delay</b>
V5 parameter	G9.9
Data Address	40116
Data type	r/w (read/write)
Units	seconds
Range	0..99

<b>Description</b>	<b>Comparator 2 OFF Delay</b>
V5 parameter	G9.10
Data Address	40117
Data type	r/w (read/write)
Units	seconds
Range	0..99

<b>Description</b>	<b>Comparator 3 Source Selection</b>
V5 parameter	G9.11
Data Address	40118
Data type	r/w (read/write)
Units	nil
Range	0..8 (See table G9.1)

<b>Description</b>	<b>Comparator 3 ON Setpoint</b>
V5 parameter	G9.12
Data Address	40119
Data type	r/w (read/ write)
Units	% of function selected
Range	0..500

<b>Description</b>	<b>Comparator 3 OFF Setpoint</b>
V5 parameter	G9.13
Data Address	40120
Data type	r/w (read/write)
Units	% of function selected
Range	0..500

<b>Description</b>	<b>Comparator 3 ON Delay</b>
V5 parameter	G9.14
Data Address	40121
Data type	r/w (read/write)
Units	seconds
Range	0..99

<b>Description</b>	<b>Comparator 2 OFF Delay</b>
V5 parameter	G9.15
Data Address	40122
Data type	r/w (read/write)
Units	seconds
Range	0..99



# SERIAL COMMUNICATION V5

## Parameters Group 10: Fault Screens

<b>Description</b>	<b>Last Fault Screen: Displays fourth, third, second &amp; first fault</b>
V5 parameter	G10.1, 2, 3, 4, 5
Data Address	40124, 40125, 40126, 40127, 40128
Data type	r(read)
Units	nil
Range	0..27 (See table 12, p.71- MT0001E_ English)

<b>Description</b>	<b>Clear History Fault</b>
V5 parameter	G10.6
Data Address	40129
Data type	r/w (read/write)
Units	nil
Range	0..1
	0 = No
	1 = Yes

## Parameters Group 11: Statistics

<b>Description</b>	<b>Total number of starts 10K</b>
V5 parameter	G11.1
Data Address	40131
Data type	r(read)
Units	nil
Range	0..9999
<b>Note:</b>	<i>Total number of starts = 10,000 x (Total of n° starts 10K + Total of n° starts).</i>

<b>Description</b>	<b>Total number of starts</b>
V5 parameter	G11.1
Data Address	40132
Data type	r(read)
Units	no
Range	0..9999

<b>Description</b>	<b>Partial number of starts 10K</b>
V5 parameter	G11.2
Data Address	40133
Data type	Only read
Units	nil
Range	0..9999
<b>Note:</b>	<i>Total number of starts = 10,000 x (Total of n° starts 10K + Total of n° starts).</i>

<b>Description</b>	<b>Partial Number of Starts</b>
V5 parameter	G11.2
Data Address	40134
Data type	r(read)
Units	nil
Range	0..9999

# SERIAL COMMUNICATION V5

**Description** **Reset Partial Number of Starts**

V5 parameter	G11.3
Data Address	40135
Data type	r/w (read/write)
Units	nil
Range	0/1
	0 = No;
	1 = Yes

**Description** **Total Working Hours 10k**

V5 parameter	G11.4
Data Address	40136
Data type	r(read)
Units	nil
Range	0..9999
<b>Note:</b>	<i>Total number of starts = 10.000 x (Total of n° starts 10K + Total of n° starts).</i>

**Description** **Total working hours**

V5 parameter	G11.4
Data Address	40137
Data type	r(read)
Units	nil
Range	0..9999

**Description** **Partial of working hours 10k**

V5 parameter	G11.5
Data Address	40141
Data type	r(read)
Units	nil
Range	0..9999
<b>Note:</b>	<i>Total number of starts = 10.000 x (Total of n° starts 10K + Total of n° starts).</i>

**Description** **Partial of working hours**

V5 parameter	G11.5
Data Address	40142
Data type	r(read)
Units	nil
Range	0..9999

**Description** **Clear Partial of Working Hours**

V5 parameter	G11.6
Data Address	40144
Data type	r/w (read/write)
Units	nil
Range	0/1
	0 = No;
	1 = Yes

**Description** **Total Faults**

V5 parameter	G11.7
Data Address	40145
Data type	r(read)
Units	nil
Range	0..9999

# SERIAL COMMUNICATION V5

<b>Description</b>	<b>Partial of Faults</b>
V5 parameter	G11.8
Data Address	40146
Data type	r(read)
Units	nil
Range	0..9999

<b>Description</b>	<b>Del Partial</b>
V5 parameter	G11.9
Data Address	40147
Data type	r/w (read/write)
Units	nil
Range	0/1
	0 = No;
	1 = Yes

<b>Description</b>	<b>Total Kw/h Counter</b>
V5 parameter	G11.10
Data Address	40148
Data type	r/w (read/write)
Units	kw/h
Range	0..9999

<b>Description</b>	<b>Total 10k Kw/h (*)Counter</b>
V5 parameter	G11.10
Data Address	40149
Data type	r/w (read/write)
Units	kw/h
Range	0..9999

**(\*) Note: All parameters including 10k are the high word of a 2 word set ,to read correctly these registers the following calculation must be done  $10.000 * (10K \text{ register value} ) = \text{High word total register} = \text{Value (high word)} + \text{Value (low word)}$ .**

## **Parameters Group 12: Slow Speed**

<b>Description</b>	<b>Slow speed mode</b>
V5 parameter	G12.1
Data Address	40151
Data type	r/w (read/write), stop to set
Units	nil
Range	0/1
	0 = No;
	1 = Yes

<b>Description</b>	<b>Slow Speed Torque</b>
V5 parameter	G12.2
Data Address	40152
Data type	r/w (read/write)
Units	%, over nominal pair of the motor
Range	30..99

# SERIAL COMMUNICATION V5

<b>Description</b>	<b>Slow Speed Timeout</b>
V5 parameter	G12.3
Data Address	40153
Data type	r/w (read/write)
Units	%, over nominal pair of the motor
Range	0..60

<b>Description</b>	<b>Slow Speed Acceleration Time</b>
V5 parameter	G12.4
Data Address	40154
Data type	r/w (read/write)
Units	seconds
Range	0..60, OFF

<b>Description</b>	<b>Slow Speed Deceleration Time</b>
V5 parameter	G12.5
Data Address	40155
Data type	r/w (read/write)
Units	seconds
Range	0..60, OFF

## Parameters Group 13: DC-Brake

<b>Description</b>	<b>DC Brake Selection</b>
V5 parameter	G13.1
Data Address	40159
Data type	r/w (read/write), stop to set
Units	no
Range	0/1 0 = No; 1 = Yes

<b>Description</b>	<b>DC Current</b>
V5 parameter	G13.2
Data Address	40160
Data type	r/w (read/write)
Units	%, of nominal current of motor
Range	30..99

<b>Description</b>	<b>DC Time</b>
V5 parameter	G13.3
Data Address	40161
Data type	r/w (read/write)
Units	seconds
Range	0..99

<b>Description</b>	<b>External Brake</b>
V5 parameter	G13.4
Data Address	40162
Data type	r/w (read/write)
Units	nil
Range	0/1 0 = No; 1 = Yes

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## Parameters Group 14: Serial Communication

<b>Description</b>	<b>Serial Communications Timeout</b>
V5 parameter	G14.1
Data Address	40164
Data type	r/w (read/write)
Units	seconds
Range	1..25, (verification OFF)

<b>Description</b>	<b>ModBus Address</b>
V5 parameter	G14.2
Data Address	40165
Data type	r/w (read/write)
Units	nil
Range	0..240

<b>Description</b>	<b>ModBus Baud rate</b>
V5 parameter	G14.3
Data Address	40166
Data type	r/w (read/write)
Units	no
Range	0..5 0 = 0; 1 = 1200; 2 = 2400; 3 = 4800; 4 = 9600; 5 = OFF

<b>Description</b>	<b>Even Parity</b>
V5 parameter	G14.4
Data Address	40167
Data type	r/w (read/write)
Units	no
Range	0/1 0 = No parity; 1 = Pair parity

## Parameters Group 15: Auto Reset .

<b>Description</b>	<b>Auto reset</b>
V5 parameter	G15.1
Data Address	40169
Data type	r/w (read/write)
Units	no
Range	0 = No 1 = Yes

<b>Description</b>	<b>Attempt number</b>
V5 parameter	G15.2
Data Address	40170
Data type	r/w (read/write)
Units	no
Range	1..5

# SERIAL COMMUNICATION V5

**Description**

V5 parameter  
Data Address  
Data type  
Units  
Range

**Reset delay time**

G15.3  
40171  
r/w (read/write)  
no  
5..120

**Description**

V5 parameter  
Data Address  
Data type  
Units  
Range

**Reset time**

G15.4  
40172  
r/w (read/write)  
no  
1..60

**Description**

V5 parameter  
Data Address  
Data type  
Units  
Range

**F1 auto RST, F2 auto RST, F3 auto RST, F4 auto RST**

G15.5, 6, 7, 8  
40173, 40174, 40175, 40176  
r/w (read/write)  
no  
0 .. 20

FAULT	FAULT LIST
0	0 NO AUTO RESET
1	1 PHAS MISING
2	2 WRONG PH/SQ
3	3 ASYM CURR
4	4 OVER LOAD
5	5 UNDER LOAD
6	6 STARTER OVT
7	7 MOTOR PTC
8	8 SHEAR PIN
9	9 OVER VOLT
10	10 UNDER VOLT
11	11 SCR_1 FAULT
12	12 SCR_2 FAULT
13	13 SCR_3 FAULT
14	14 SCR_S FLT
15	15 EXCESIV LS T
16	16 COMMS T/OUT
17	17 EXTERN TRIP
18	18 CUR FLT
19	19 CUR2 FLT
20	20 ALL THE FLTS

**Parameters Group 16: Pump control 1.**

**Description**

V5 parameter  
Data Address  
Data type  
Units  
Range

**Irrigation time setting**

G16.1  
40212  
r/w (read/write)  
hours  
0 to 60 h

# SERIES COMMUNICATION V5

**Description**  
V5 parameter  
Data Address  
Data type  
Units  
Range

**Irrigation time display**  
G16.2  
40213  
r/w (read/write)  
hours  
0 to 60 h

**Description**  
V5 parameter  
Data Address  
Data type  
Units  
Range

**Start mode selection**  
G16.3  
40214  
r/w (read/write)  
no  
0 = Display unit  
1 = 2 Wire

**Description**  
V5 parameter  
Data Address  
Data type  
Units  
Range

**High pressure timeout**  
G16.4  
40215  
r/w (read/write)  
seconds  
0 to 60

**Description**  
V5 parameter  
Data Address  
Data type  
Units  
Range

**Low pressure timeout**  
G16.5  
40216  
r/w (read/write)  
seconds  
0 a 3600

**Description**  
V5 parameter  
Data Address  
Data type  
Units  
Range

**Low pressure Bypass time**  
G16.6  
40217  
r/w (read/write)  
seconds  
0 a 1800

**Description**  
V5 parameter  
Data Address  
Data type  
Units  
Range

**No flow Bypass time**  
G16.7  
40218  
r/w (read/write)  
seconds  
0 to 1800

**Description**  
V5 parameter  
Data Address  
Data type  
Units  
Range

**No flow debounce time**  
G16.8  
40219  
r/w (read/write)  
seconds  
0 to 60

**Description**  
V5 parameter  
Data Address  
Data type  
Units  
Range

**Deep well probe Bypass timer**  
G16.9  
40220  
r/w (read/write)  
seconds  
0 to 60

# SERIES COMMUNICATION V5

## 5. ADDRESSING MODES.

### 5.1 Broadcast addressing mode.

Broadcast addressing mode allows master to access at the same time to all slaves connected to the ModBus net.

Broadcast addressing mode which admits this global addressing mode is:

**Function 16**

**Registers writing.**

In order to access to all soft-starters in a ModBus net, address zero (0) should be used. When this address is used, all slaves in ModBus net make the required task but they do not prepare any answer.

### 5.2 Groupcast addressing mode.

Groupcast addressing mode allows master to access at the same time to a group of slaves connected to the ModBus net.

The ModBus function code which admits this group addressing mode is:

**Function 16**

**Registers writing.**

In order to access to different soft-starters groups in a ModBus net, a special addressing system is used. This system obtains the linked group address starting from individual addresses.

In the following table the corresponding between individual addresses and linked group address is shown.

GROUP	INDIVIDUAL ADDRESS	GROUP ADDRESS	GLOBAL ADDRESS
Group 1	1..6	241	0
Group 2	17..32	242	0
Group 3	33..48	243	0
Group 4	49..64	244	0
Group 5	65..80	245	0
Group 6	81..96	246	0
Group 7	97..112	247	0
Group 8	113..128	248	0
Group 9	129..144	249	0
Group 10	145..160	250	0
Group 11	161..176	251	0
Group 12	177..192	252	0
Group 13	193..208	253	0
Group 14	209..224	254	0
Group 15	225..240	255	0

Table 4.1 V5 soft-starters communication addresses



# *SERIES COMMUNICATION V5*

## **ANNEX A. PHYSICAL LEVEL**

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V5 soft-starter can be physically connected to a RS485 net, where more equipments cohabit, by means of a twisted wire.

RS232 hardware has two separate lines, one of them for receiving (Rx) and the other one for transmitting (Tx). This allows RS232 net to work in full duplex mode. Full duplex means master is able of transmitting and receiving data simultaneously.

RS485 hardware used in V5 soft-starter uses the same twisted wire for receiving (Rx) and for transmitting (Tx) and that allows RS485 system to work only in half duplex. Half duplex means master is able of transmitting or receiving data, but no simultaneously. In order to control information flow through a half duplex system in a RS232 net, the normally used line is Request – To – Send (RTS) line.

# SERIES COMMUNICATION V5

## ANNEX B. MODBUS COMMUNICATION PROTOCOL.

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### B.1 FRAMING RTU

In framing RTU, data are transmitted and received like 8 bits sequences. When a 16 bits register is wanted to be transmitted, it is divided in to two parts of 8 bits, transmitting first the most significant byte. If more than 3.5 byte periods are lapsed between characters reception, soft-starter will understand that the following received byte belongs to a different frame and will considered the current frame finished.

### B.2 ADDRESSES FIELD

Addresses field has a 8 bits length and allows to address 1-240 individual addresses, 241-255 group addresses, and one (0) broadcast address.

Each V5 soft-starter identifies itself by unequivocal way with an address that master uses when communications must be established.

All V5 soft-starter recognise and execute messages with groupcast addresses, but they do not answer master with a confirmation.

### B.3 FUNCTION FIELD

Function field indicates to the addressed equipment task to be done. When slave detects a communication failure, most significant bit of this field is set to one in order to indicate to the master the no normal situation. In point B.6 you can get additional information about exception codes.

### B.4 DATA FIELD

Data field is used for transmitting information to and from addressed slaves. Data field length is 16 (or multiple) bits length (transmitted in 2 bytes, first most significant).

### B.5 CYCLICAL REDUNDANT CODE

Cyclical redundant code is used as much for the master as for the slave in order to detect failures in transmitting. This code is added at the end of transmitted frame. The characteristic polynomial of this code is:

$$\text{CRC} - 16 = x^{16} + x^{15} + x^2 + 1$$

Receiver calculates the CRC of received message and compares it with received cyclical redundant code. In case of failure, the complete message is rejected. It is no possible to recover failures inside of this message.

#### Theory.

All the message (without start / stop and parity bits) is consider like a continuous sequence to be processed with most significant bit transmitted at first place. The message is pre-multiplied per  $2^{16}$  (2 bytes to the left) and then it is divided by polynomial shown above. The quotient is discarded and the rest of 16 bits is added to the message. This rest is pre-initialized to 0FFFFH in order to avoid the acceptance of a zeros sequence like a valid sequence.

# SERIES COMMUNICATION V5

Receiver receives the whole sequence and makes the division using the same characteristics polynomial: in case of received message has no error, the rest of division is zero.

The device used for data series transmission will send the less significant bit LSB of each character first of all. When the CRC should be generated, the first transmitted bit is defined like most significant bit MSB of dividend. By convenience, and due to no haulage in this arithmetic, it is assumed that most significant bit MSB is the one on the right. For that, if we want to be consistent, bit order of characteristic polynomial should be inverted. Most significant bit is discarded just because it affects only to quotient and no to rest. At the end, the original polynomial  $x^{16}+x^{15}+x^2+1 = 1100\ 0000\ 0000\ 00101$  left in this way  $1010\ 0000\ 0000\ 0001$  (A001H).

## B.6 EXCEPTION CODES

So much protocol errors like range data errors cause a response of V5 soft-starter with an exception response.

A exception response consist of the slave address which has detected the failure, the function code received by the slave (with most significant bit set to 1 in order to indicate an exception response), the error code and the cyclical redundant code.

In the following table the exception codes and their causes are summarized:

CODE	NAME	CAUSE
01	Illegal function	Function field received by slave is out of range. Valid range for function code is code 3 and 16.
02	Illegal data address	Data address received by the slave is out of range.
03	Illegal data value	Data value received by the slave is out of range.
06	Occupied, rejected message	Slave can not achieve the required task by master in an immediate way.
07	Acknowledge	The required task can not be carried out.

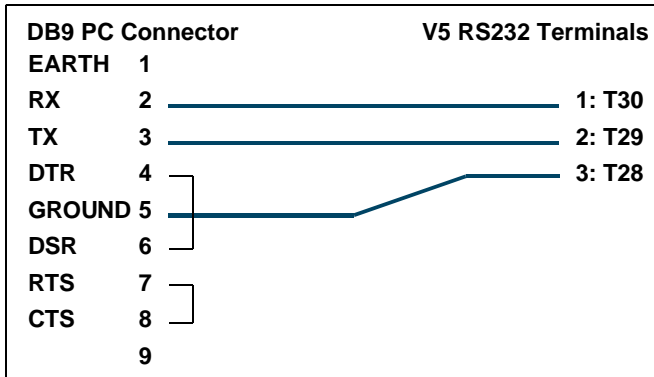
# SERIES COMMUNICATION V5

## ANNEX C. TYPICAL CONNECTION DRAWING

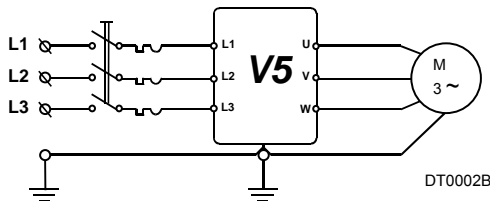
### Typical connection drawing.

Pin out and connections for multiplexer bridge Modicon BM85 to communications port RS232. This pin out is also applicable to 9 pins output connector in compatible IBM computers.

CONNECTOR		CONNECTION
1	-	Chassis.
2	IN	RX.
3	OUT	TX.
4	OUT	DTR (Data Terminal Ready).
5	-	Earth signal.
6	IN	DSR (Data Set Ready).
7	OUT	RST (Request To Send).
8	IN	CTS (Request To Send).
9	-	Not Connected.



DT0175A



# SERIES COMMUNICATION V5

## Delegations

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